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1. **On covariances for fusing laser rangers and vision with sensors onboard a moving robot**
   Nygards, J.; Wernersson, A.;
   Intelligent Robots and Systems, 1998. Proceedings., 1998 IEEE/RSJ International Conference on
   Volume 2, 13-17 Oct. 1998 Page(s):1053 - 1059 vol.2
   **IEEE CNF**

2. **A simulation environment to test fuzzy navigation strategies based on perceptions**
   Garcia-Perez, L.; Garcia-Alegre, M.C.;
   Fuzzy Systems, 2001. The 10th IEEE International Conference on
   Volume 2, 2-5 Dec. 2001 Page(s):590 - 593 vol.3
   **IEEE CNF**

3. **Localizing mobile RF targets using multiple unmanned aerial vehicles with heterogeneous sensing capabilities**
   Pack, D.; York, G.; Toussaint, G.;
   Networking, Sensing and Control, 2005. Proceedings. 2005 IEEE
   19-22 March 2005 Page(s):632 - 637
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1. **Conceptual design of an integrated laser-optical measuring system for flexible manipulator**
   Xu, W.L.; Tso, S.K.; Wang, X.S.;
   Systems, Man, and Cybernetics, 1996., IEEE International Conference on
   Volume 2,  14-17 Oct. 1996 Page(s):1247 - 1252 vol.2
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the **robot** has at least one motor for manipulating a **linkage controlling** the ...
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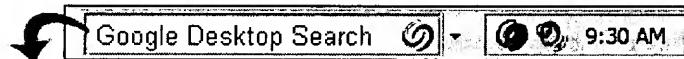
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